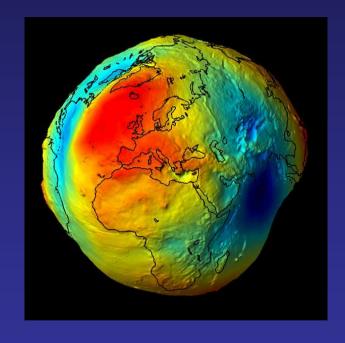
# About the MacCullagh relations in Relativity

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# MacCullagh relations in the Newtonian framework



Earth's rotation



Earth's gravity field

### Newtonian MacCullagh relations: spherical representation

$$egin{array}{lcl} C_{21} &=& -rac{I_{13}}{Ma^2} \ S_{21} &=& -rac{I_{23}}{Ma^2} \ C_{22} &=& rac{I_{22}-I_{11}}{4Ma^2} \ S_{22} &=& -rac{I_{12}}{2Ma^2} \ C_{20} &=& rac{1}{Ma^2} \left(rac{I_{11}+I_{22}}{2}-I_{33}
ight) \end{array}$$

$$U(\mathbf{x}) = \left(\frac{GM}{r}\right) \sum_{l=0}^{\infty} \sum_{m=0}^{l} \left(\frac{a}{r}\right)^{l} P_{lm}(\cos\theta) (C_{lm}\cos m\phi + S_{lm}\sin m\phi)$$

$$I_{ij} = \int_B d^3x 
ho(\mathbf{x}^2 \delta_{ij} - x^i x^j)$$

#### Newtonian MacCullagh relations: Cartesian coordinates

$$M_{ij} = -\mathrm{STF}(I_{ij})$$

$$U(\mathbf{x}) = G \sum_{l=0}^{\infty} \frac{(2l-1)!!}{l!} M_L \frac{\hat{n}_L}{r^{l+1}}$$

$$\hat{n}_L \equiv \frac{\hat{x}^L}{r^l}$$

$$\hat{x}^L \equiv \hat{x}^{i_1 \dots i_l} = \text{STF}_{i_1 \dots i_l} \left( x^{i_1} \dots x^{i_l} \right)$$

$$\hat{x}^{ij} \equiv \text{STF}_{i,j}(x^i x^j) = x^i x^j - \frac{1}{3} \delta_{ij} \mathbf{x}^2$$

# Relativity

Post-Newtonian framework (DSX)

#### Blanchet-Damour quadrupole mass moment

$$M_{ij} = \int_{B} d^{3}x \hat{x}_{ij} \sigma + \frac{1}{14c^{2}} \frac{d^{2}}{dt^{2}} \int_{B} d^{3}x \hat{x}_{ij} \mathbf{x}^{2} \sigma - \frac{20}{21c^{2}} \frac{d}{dt} \int_{B} d^{3}x \hat{x}^{ijk} \sigma^{k}$$

$$\sigma \equiv \frac{T^{00} + T^{ss}}{c^2}, \quad \sigma^i \equiv \frac{T^{0i}}{c}$$

A post-Newtonian spin vector was defined in DSX III

$$S_i = \epsilon_{ijk} \int_B d^3x \, x^j \left[ \sigma^k \left( 1 + \frac{4U}{c^2} \right) - \frac{\sigma}{c^2} \left( 4V^k - \frac{1}{2}Q^k \right) \right]$$

$$V^{k}(\mathbf{x}) \equiv G \int_{B} d^{3}x' \frac{\sigma^{k}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|}$$

$$Q^{k}(\mathbf{x}) \equiv G \int_{B} d^{3}x' \, \sigma^{l}(\mathbf{x}') \frac{\delta_{kl} - n_{xx'}^{k} n_{xx'}^{l}}{|\mathbf{x} - \mathbf{x}'|}$$

$$n_{xx'}^{k} \equiv \frac{(x - x')^{k}}{|\mathbf{x} - \mathbf{x}'|}$$

From this a post-Newtonian moment of inertia tensor can be derived

## Question

Is the Newtonian relation

$$M_{ij} = -\mathrm{STF}(I_{ij})$$

valid also to post-Newtonian order?

To answer this questions we employed a specific Newtonian model for the 1/c2 terms:

a homogeneous oblate spheroid with b (in z-direction) <=

the internal graviational potential U is given by

$$U(\mathbf{x}) = \pi G \rho \left[ \mathcal{I} - \mathcal{A}(x^2 + y^2) - \mathcal{B}z^2 \right]$$

where

$$\mathcal{A} = \frac{(1-e^2)^{1/2}}{e^3} \arcsin(e) - \frac{1-e^2}{e^2} = \frac{2}{3} - \frac{2}{15}e^2 - \frac{8}{105}e^4 + \dots$$

$$\mathcal{B} = \frac{2}{e^2} - \frac{2(1-e^2)^{1/2}}{e^3} \arcsin(e) = \frac{2}{3} + \frac{4}{15}e^2 + \frac{16}{105}e^4 + \dots$$

 $(2\mathcal{A} + \mathcal{B} = 2)$  and

$$\mathcal{I} = 2\mathcal{A}a^2 + \mathcal{B}b^2.$$

The geometrical eccentricity e of the spheroid is given by

$$e^2 = 1 - \frac{b^2}{a^2}$$
.

#### **RESULT**

$$M_{ij} \neq -\text{STF}(I_{ij})$$

For our model:

$$M_{ij} = -\text{STF}(I_{ij}) - \left(\frac{148}{875}e^2\right) \left(\frac{GM}{c^2a}\right) (Ma^2) \hat{e}_{ij} + \mathcal{O}(e^4)$$

$$\hat{e}_{ij} \equiv \operatorname{diag}(1, 1, -2)$$

#### PN MacCullagh relations, spherical representation

For our specific model only one MC relation needs to be modified

$$C_{20}^* = \frac{1}{Ma^2} \left( \frac{I_{11} + I_{22}}{2} - I_{33} \right)$$

$$C_{20}^* = C_{20} - \frac{444}{875} \left( \frac{GM_{\odot}}{c^2 a} \right) e^2$$



δ - term

#### Numbers for the Earth:

$$e^2 = 0.0066944$$

Taking the EGM96 value for  $GM_{\oplus}$  (3.986004418 · 10<sup>14</sup> m<sup>3</sup>s<sup>-2</sup>) the relativistic scale factor reads

$$\left(\frac{GM_{\oplus}}{c^2a}\right) = 6.9534851 \cdot 10^{-10}$$

so that

$$\delta \equiv rac{444}{875} \left(rac{GM_{\oplus}}{c^2 a}
ight) e^2 = 2.362 imes 10^{-12}$$

#### Implications for a post-Newtionian SMART-97 like nutation model

In SMART97 GEM-T3 values for the potential coefficients are used:

$$C_{20} = -1082.62607459 \times 10^{-6}$$
  
 $C_{22} = 1.57441020 \times 10^{-6}$   
 $S_{22} = -0.90375718 \times 10^{-6}$ 

The principle moments of interia, A, B and C are obtained in the following way: one starts with a certain initial value for C:

$$C = 0.180548385370 \times 10^{-14} M_{\odot} AU^{2}$$

where  $M_{\odot}$  is the mass of the Sun,

$$\frac{M_{\odot}}{M_{\oplus}} = 332\,946.045\,,$$

and the astronomical unit, AU, was taken as

$$AU = 149597870610 \,\mathrm{m}$$

B-A is then obtained from

$$\frac{B-A}{M_{\oplus}a^2} = 4\sqrt{C_{22}^2 + S_{22}} = 7.261454 \times 10^{-6}$$

that would still be valid relativistically (note, that that the potential coefficients refer to axes that differ in the equatorial plane by an angle  $\alpha=14^{\circ}.95$  (West) with respect to the principle axes of inertial). Then the Newtonian MacCullagh relation for the dynamical ellipticity  $H_d$  is used for SMART97:

$$H_d \equiv \frac{2C - A - B}{2C} = -M_{\oplus} a^2 \frac{C_{2,0}}{C}$$

that leads to

$$A = 0.179955329763 \times 10^{-14} M_{\odot} \text{AU}^2$$
  
 $B = 0.179959294245 \times 10^{-14} M_{\odot} \text{AU}^2$ 

If the post-Newtonian MacCullagh relation (30) is used one would get

$$A = 0.179955329761 \times 10^{-14} M_{\odot} \text{AU}^2$$
  
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12th digit after the comma

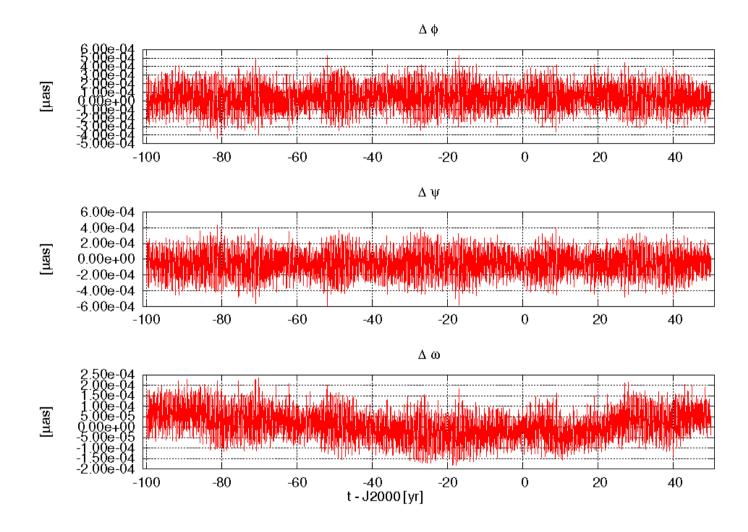


Figure 1: Differences (without  $\delta$ / with  $\delta$ ) for the three Euler angles  $\Delta \phi$ ,  $\Delta \psi$  and  $\Delta \omega$  are shown as functions of time. The  $\delta$  was magnified by a factor of 1000, so that effects for the real Earth will be about one thousand times smaller.

# **CONCLUSION**

A violation of the classical Mac Cullagh relations in Relativity can safely be neglected for a post-Newtonian Prec/Nut theory at 0.1 µas accuracies